Selection Criteria for General Linear Motion Systems



- · What is the accuracy/repeatability requirement?
- Are these values realistic, based upon the desired motion profile?

Orient	• How will the system be mounted ("normal", on its side, inverted, vertical, etc.)? • How will this affect the load requirements?
Speed aka: velocity, acceleration, motion pro	<ul> <li>What is the maximum speed and acceleration required?</li> <li>What is the maximum jerk allowable?</li> <li>What motion profile (shape) is desired?</li> </ul>
<b>Travel</b> aka: stroke, over-travel, envelope	<ul> <li>What is the required travel (stroke)?</li> <li>What is the overall envelope allowed?</li> <li>How much over travel (safety zone) is required?</li> </ul>
Load	<ul> <li>What is End of Arm Tooling (EOAT) and where is it located?</li> <li>What additional forces are seen by the system during use (e.g., cutting or pushing forces)?</li> <li>What do the static and dynamic free body diagrams look like? Are all loads considered?</li> <li>What is expected of the system after an impact?</li> </ul>
Unkno	• What could possibly go wrong?

- · How will someone misuse this system?
- What else could go wrong (Repeat this question to further explore)?

## **Duty/Life Cycle**

· What is the actual duty cycle for the system? · What is the expected lifetime?

## Environment

- · What environment will the system be installed? · Are there hazards in the environment?
- · Will the system disburse contaminants?
- · What's the maintenance schedule?
- · Is the system accessible for maintenance/lubrication?

Safety

aka: accuracy, repeatability

- Are there any safety standards to which the system needs to conform?
- · What could happen if the system fails?
- · Are there safeguards that need to be installed for a system failure?
- · Could people be injured by this system? Are there installed safety features?

